

**MESA Founding Committee Sign-up Sheet
(Sept. 06, 2007, Rio Hotel, Las Vegas)**

Name (First Last)	Institution	E-mail address	Research area(s)
Harry H. Cheng	University of California, Davis	hhcheng@ucdavis.edu	Infrastructure and mobile agent technology for mechatronic and embedded systems
YangQuan Chen	Utah State University, USA	yqchen@ece.usu.edu	Controls, Mechatronics
Lei Zuo	Abbott Laboratories, USA	leizuo@alum.mit.edu	Controls, vibration, biomechanics
Zuomin Dong	Univ. of Victoria, Canada	zdong@me.uvic.ca	CAD/CAE/CAM Hybrid vehicles, Fuel cells
Xiaoqi Chen	Univ. of Canterbury, New Zealand	xiaoqi.chen@canterbury.ac.nz	Mechatronics, robotics, mobile machines
Primo Zingaretti	Politechnic Univ. of Rache Ancona, Italy	zinga@diiga.univpm.it	Mobile robotics (UW, ground, air vehicles)
Dumitru Baleanu	Cankaya Univ. Ankara, Turkey	dumitru@cankaya.edu.tr	Fractional Dynamics
J.A.Tenreiro Machado	Institute of Engineering of Porto, Portugal	jtm@isep.ipp.pt	Non-linear Dynamics, Mechatronics, Intelligent systems
Jian S. Dai	King's College London, Univ. of London, UK	jian.dai@kcl.ac.uk	Kinematics, mechanisms, robotics, mechatronics
Martin Horauer	Univ. of Applied Sciences, Technikum, Vienna	horauer@ieee.org	Embedded Systems
Ayman Gendy	Univ. of Leicester, UK	Akg14@LE.AC.uk	Embedded Systems
Riccardo Caponetto	Univ. of Catania, Italy	riccardo.caponetto@dees.unict.it	Controls, Embedded Systems
Wen Chen	Hohai University, China	chenwen@hhu.edu.cn	Computational Mechanics/ Damping Mechanics
Changhwa Cho	Texas A&M Univ. CS, TX, USA	changhwa@tamu.edu	Dynamics & control of nonlinear systems
Sehoon Oh	Univ. of Tokyo, Japan	sehoon@horilab.iis.u-tokyo.ac.jp	Control design, welfare application

Yo-Chol Lee	ETRI, Korea	yclee@etri.re.kr	Mobile robot navigation
Hyo-Sung Ahn	Gwangju Institute of Science and Technology, Korea	hyosung@gist.ac.kr	Mobile robotics, control
Kwun-Lon Ting	Tennessee Tech University, USA	kting@tntech.edu	Compliant mechanism, mechanism
Hong Zhou	Texas A&M Univ. – Kingsville, USA	hong.zhou@tamuk.edu	Mechanisms, robotics
Xianwen Kong	Heriot-Watt Univ. UK	x.kong@hw.ac.uk	Mechanisms, robotics
Bo Chen	Michigan Tech Univ., USA	bochen@mtu.edu	Mechatronics and embedded systems
Hong Duan	Univ. of California, Davis, USA	hduan@ucdavs.edu	Mechanical and electronic systems
Yu-Cheng Chou	Univ. of California, Davis, USA	cycchou@ucdavs.edu	Mobile agent technology, mechatronic and embedded systems
David Ko	Univ. of California, Davis, USA	dko@ucdavs.edu	Mobile agent technology,
Stephen Nestinger	Univ. of California, Davis, USA	thestinger@ucdavis.edu	Robotics, Mechatronics, Embedded Systems, mobile agents
Jeffrey Mountain	University of Texas at Tyler, USA	mountain@uttyler.edu	Mechatronics, Embedded System, Applications
Calvin Coopmans	Utah State University, USA	coopmans@gmail.com	Embedded space systems, fractional order control
Shelley Rounds	Utah State University, USA	shelleyr@cc.usu.edu	Controls, Swarm engineering
Varsha Bhambhani	Utah State University, USA	bhambhani_varsha@rediffmail.com	Robotics, Fractional order control
Austin Jensen	Utah State University, USA	ajen@cc.usu.edu	Embedded Systems, Image processing, UAV
Abdollah	Utah State	abdshafiee@cc.usu.edu	Structural control & health monitoring

Shafieezadeh	University, USA		
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