Call for Papers



Symposium on Biomechatronics – Medical Devices & Technologies

as part of the 7^{th} ASME/IEEE International Conference on

Mechatronic and Embedded Systems and Applications

August 29-31, 2011 Washington, DC, USA http://iel.ucdavis.edu/mesa/MESA11/

Objectives: The symposium provides a cross-disciplinary platform for presenting the latest developments in biomechatronics and robot assistive technologies for medical and bio-applications. It relates to the design of systems, devices and products for use as assistive tools when interacting with humans and biosystems. Particular topics of interest include, but are not limited to:

- Biomechatronics Design, Biomedical Robotics, Robotics for Medical Surgery
- Rehabilitation Robotics, Robotics for Stroke Patients and Wearable Medical Devices, Assistive Technology for Injured, Elderly and Disabled
- Microelectronics, Health Monitoring Devices, Embedded Signal Processing, Low-power Design
- Bioelectromagnetism, Electrical Bioimpedance, Implantable Electronics
- Biorobotics, Biomaterials, Biosensors & MEMS, Biomechanical Devices
- New Materials, New Sensing and Actuation Technology for Biomechatronic Systems
- Medical Imaging and Visualisation, Simulation and Navigation, Virtual Reality, Intuitive Command and Control Systems, Haptics and Sensor Technologies
- Biomechatronic System Modelling, Simulation of Bio-Systems, System Identification
- Biomechanics Study and Modelling
- Interaction between Devices and Humans, Adaptive Control Methods

Paper Submission: Manuscripts shall be no longer than 10 pages and shall adhere to the ASME author guidelines. Word and LaTeX templates are available from ASME to assist authors in preparing their papers for publication. Final papers in PDF format must be electronically submitted to: https://www.asmeconferences.org/IDETC2011

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Important Dates:

| Submission of Abstract | 11-02-2011 |
|-----------------------------------|------------|
| Submission of Full-Length Paper | 18-02-2011 |
| Author Notification of Acceptance | 20-05-2011 |
| Submission of Copyright Form | 27-05-2011 |
| Submission of Final Paper | 30-05-2011 |

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Technical Co-Sponsors:

ASME Division of Design Engineering IEEE Intelligent Transportation Systems Society IEEE Control Systems Society



