Call for Papers



Symposium on Autonomous Systems & Ambient Intelligence

as part of the 7^{th} ASME/IEEE International Conference on

Mechatronic and Embedded Systems and Applications

August 29-31, 2011 Washington, DC, USA http://iel.ucdavis.edu/mesa/MESA11/

Objectives: Implementation of autonomous systems is still a tough and challenging topic in mechatronic systems. To improve autonomous capabilities like intelligent navigation and distributed decision, recently, the concept of ambient intelligence has been introduced. The key point herein is to utilize wireless sensors or distributed embedded networks to improve the recognition capabilities of mobile vehicles or robots.

Papers describing original, previously unpublished research work, experimental efforts, practical experiences, and industrial and commercial developments with regard to autonomous systems and ambient intelligence are solicited. Particular topics of interest include, but are not limited to:

- Autonomous navigation and control
- Robot intelligence
- Reinforcement learning
- Multi-agent systems

- Teleoperation & coordination
- Distributed Control Systems
- Indoor localization
- Wireless sensor networks

Paper Submission: Manuscripts shall be no longer than 10 pages and shall adhere to the ASME author guidelines. Word and LaTeX templates are available from ASME to assist authors in preparing their papers for publication. Final papers in PDF format must be electronically submitted to: https://www.asmeconferences.org/IDETC2011

Accepted, peer-reviewed manuscripts will be published in the conference proceedings and EI indexed.

Contact Information:

Hyo-Sung Ahn, Ph.D. School of Mechatronics Gwangju Institute of Science and Technology

P: +82 (62) 970-2398 E: hyosung@gist.ac.kr I: http://dcas.gist.ac.kr Yu Zhou, Ph.D.

Department of Mechanical Engineering State University of New York at Stony Brook

P: +1 (631) 632-8322

E: yuzhou@notes.cc.sunysb.edu I: http://me.eng.sunysb.edu

Important Dates:

Submission of Abstract 11-02-2011 Submission of Full-Length Paper 18-02-2011 Author Notification of Acceptance 20-05-2011 Submission of Copyright Form 27-05-2011 Submission of Final Paper 30-05-2011

Technical Co-Sponsors:

ASME Division of Design Engineering IEEE Intelligent Transportation Systems Society IEEE Control Systems Society



